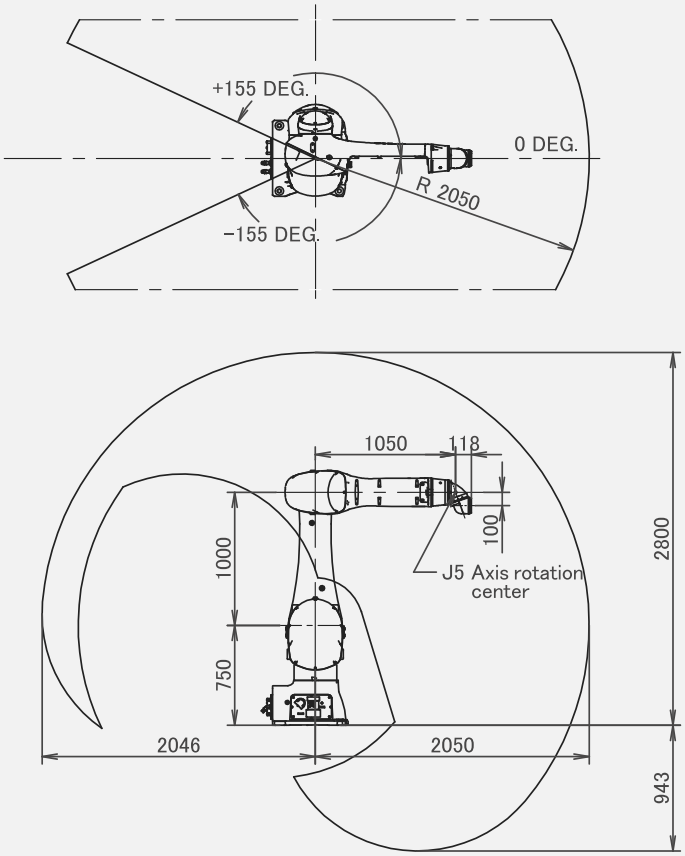
P-55/15-21A

Max. load capacity at wrist: **15 kg**

Max. reach: **2050 mm**

Controlled axes	Repeatability (mm)	Mechanical weight *1 (kg)	Motion range (°)						Maximum speed (°/s)*2						J4 Moment/ Inertia (Nm/kgm2)	J5 Moment/ Inertia (Nm/kgm2)	J6 Moment/ Inertia (Nm/kgm2)
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6			
6	± 0.07	430	310	215	220	1080	1080	1080	125	125	125	375	430	545	65/3	55/2.1	11.5/0.35

Working range



Robot	**P-55/15-21A**
Robot footprint [mm]	-
Mounting position Floor	●
Mounting position Invert	●
Mounting position Wall	●
Mounting position Angle	●

Controller	**R-50*i*A**
Mate cabinet	-
A-cabinet	-
B-cabinet	-
C-cabinet	●
*i*Pendant	●

*1) Without controller. *2) During short distance motions, the axis speed may not reach the maximum value stated.

● standard ○ on request - not available [ ] with hardware and/or software option

Technical information subject to changes without prior notice. All rights reserved. ©2026 FANUC Europe Corporation