Ultimate reach, fast precision handling M-10*i*D/10L





Fast accurate handling for maximum productivity

- high productivity and precision thanks to higher rigidity
- compact and fully articulated to reach narrow spaces in machine tools or jigs
- ideal solution for compact production line installations
- easy installation and seamless fully integrated cable routing to eliminate interference from peripherals and work cell equipment
- intelligent maintenance schedule with FANUC Zero Downtime function that predicts mechanical and process equipment status

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M-10*i*D/10L (Hollow wrist)

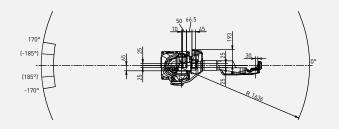


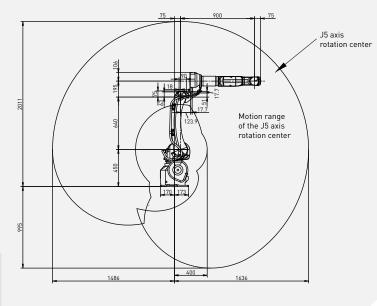


			Motion range (°)							Ma	ximum	speed (°	?/s)				
Controlled axes	Repeatability (mm)	Mechanical weight (kg)	J1	J2	73	J4	J5	J6	J1	J2	73	J4	J5	J6	J4 Moment/ Inertia (Nm/kgm²)	J5 Moment/ Inertia (Nm/kgm²)	J6 Moment/ Inertia (Nm/kgm²)
6	± 0.03*	150	340 (370)	235	455	380	280 (360) *21)	540 (900) *21)	260	240	260	430	450	720	22.0/0.65	22.0/0.65	9.8/0.17

Working range

Motion range may be restricted according to the mounting angle!





🚊 Robot	M-10 <i>i</i> D/10L
Robot footprint [mm]	343 x 343
Mounting position Floor	•
Mounting position Upside down	•
Mounting position Angle	•
Eontroller	R-30 <i>i</i> B Plus
Open air cabinet	-
Mate cabinet	0
A-cabinet	•
B-cabinet	0
iPendant Touch	•
Electrical connections	
Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	1
Integrated services	
Integrated signals on upper arm In/Out	8/8
Integrated air supply	1
Environment	
Acoustic noise level [dB]	< 70
Ambient temperature [° C]	0-45
Protection	
Body standard/optional	IP54 /IP55
Wrist & J3 arm standard/optional	IP67

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* 21) Extended range for external cable type